

Package ‘PPTS’

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Title Point Process Time Series

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Description Provides functions for point process time series. Autocorrelation functions for spatial and temporal time series, and estimation of trend-plus-seasonality models for temporal and spatial time series. See Gervini (2025) <[doi:10.1111/jtsa.70018](https://doi.org/10.1111/jtsa.70018)> and Gervini and Kopschke (2026) <[doi:10.48550/arXiv.2605.21884](https://doi.org/10.48550/arXiv.2605.21884)>.

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PPTS-package

Provides functions for point process time series.

Description

ACF for spatial and temporal time series, estimation of trend-only and trend-plus-seasonality for temporal and spatial time series, and respective confidence intervals.

Author(s)

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acf_sPP

Autocorrelogram for spatial point-process time series

Description

Spatial binned autocorrelograms.

Usage

```
acf_sPP(x, rng, kmax = 10*log10(length(x)), nbin = 9,
        alpha = 0.05, MC = 10000, no.plot = FALSE)
```

Arguments

x	(n-list) Observations ($x[[i]]$ is a $m_i \times 2$ matrix, possibly $m_i=0$, first column is longitude, second column is latitude)
rng	(4-vector) Spatial range of the process (first two numbers are longitude range, the other two are latitude range)
kmax	(int ≥ 0) Maximum lag (default $10 \cdot \log_{10}(n)$)
nbin	(int ≥ 4) Number of bins for binned estimator (default 9) (if not a perfect square integer, the closest perfect square is used)
alpha	(scalar) Significance test level
MC	(integer) Number of Monte Carlo replications for significance threshold computation (Default 10,000. Use MC=0 if no threshold computation is desired)
no.plot	(logical) Plot is shown if FALSE (default)

Value

lag	(kmax-vector) Lags at which autocorrelations are computed (1:kmax)
rho	(kmax-vector) Autocorrelations at lags 1:kmax
thr	(scalar) Significance threshold

Author(s)

Daniel Gervini

References

Gervini, D. (2025), "Autocorrelation functions for point-process time series", Journal of Time Series Analysis, DOI: 10.1111/jtsa.70018

Examples

```
data(crime)
acf_sPP(x=crime$x, rng=crime$range)
```

 acf_tPP

Autocorrelogram for temporal point-process time series

Description

Temporal binned autocorrelograms.

Usage

```
acf_tPP(x, rng, kmax = 10*log10(length(x)), nbin = 5,
        alpha = 0.05, MC = 10000, no.plot = FALSE)
```

Arguments

x	(n-list) Observations (x[[i]] is a vector of length mi, possibly mi=0)
rng	(2-vector) Time range of the process
kmax	(int>=0) Maximum lag (default 10*log10(n))
nbin	(int>=0) Number of bins for binned estimator (default 5)
alpha	(scalar) Significance test level
MC	(integer) Number of Monte Carlo replications for significance threshold computation (Default 10,000. Use MC=0 if no threshold computation is desired)
no.plot	(logical) Plot is shown if FALSE (default)

Value

lag	(kmax-vector) Lags at which autocorrelations are computed (1:kmax)
rho	(kmax-vector) Autocorrelations at lags 1:kmax
thr	(scalar) Significance threshold

Author(s)

Daniel Gervini

References

Gervini, D. (2025), "Autocorrelation functions for point-process time series", *Journal of Time Series Analysis*, DOI: 10.1111/jtsa.70018

Examples

```
data(bikes)
acf_tPP(x=bikes$x, rng=bikes$range)
```

bikes

Divvy Bike Rides

Description

Daily bicycle check-out times (Jan 1, 2016 to Dec 31, 2016) at Ashland & Wrightwood station of the Divvy bike-sharing system in the city of Chicago.

Usage

```
data("bikes")
```

Format

A list with two elements: range (vector of length 2) and x (list of length 366).

Details

Vector `bikes$range` indicates time range used for some (but not all) analyses in the paper. List `bikes$x` contains the daily bike check-out times as vectors, with time given in hours in the $[0,24)$ range.

Source

Chicago Data Portal, <https://data.cityofchicago.org/>

References

Gervini, D. (2025). Autocorrelation functions for point-process time series. *Journal of Time Series Analysis*. DOI: 10.1111/jtsa.70018.

Gervini, D. and Kopischke, S.A. (2026). Trend and seasonality estimation for point-process time series. DOI: 10.48550/arXiv.2605.21884

NSF DMS 2412015: "Statistical methods for point-process time series".

Examples

```

require(PPTS)
data(bikes)
oldpar <- par(no.readonly = TRUE)
fit <- trend_seas_t(x=bikes$x, rng=c(4,24), d=7, c.deg=3, sp.nk=5, maxit=10000)
par(mfrow=c(2,1), mar=c(4,4,1,1), mgp=c(2,1,0))
plot(fit$tt, exp(fit$ct), type="l", xlab="t (day)", ylab="exp(c(t))")
title(main="Multiplicative trend")
matplot(fit$u, exp(fit$mus), type="l", lty=1, xlab="u (hour)", ylab=expression(nu[j](u)))
title(main="Baseline seasonal intensities")
par(oldpar)

```

crime

Chicago Street Theft

Description

Daily street theft locations in the North side of Chicago for the year 2014.

Usage

```
data("crime")
```

Format

A list with two elements: range (vector of length 4) and x (list of length 365).

Details

Vector `crime$range` (W longitude, E longitude, S latitude, N latitude) indicates spatial range used for the analyses in the paper.

List `crime$x` contains locations of daily incidents in matrix form (each row corresponds to a different incident, columns are longitude-latitude coordinates)

Source

Chicago Data Portal, <https://data.cityofchicago.org/>

References

Gervini, D. (2025). Autocorrelation functions for point-process time series. *Journal of Time Series Analysis*. DOI: 10.1111/jtsa.70018.

Gervini, D. and Kopischke, S.A. (2026). Trend and seasonality estimation for point-process time series. DOI: 10.48550/arXiv.2605.21884

NSF DMS 2412015: "Statistical methods for point-process time series".

Examples

```

require(PPTS)
data(crime)
fit <- trend_seas_s(x=crime$x, rng=crime$range, d=1, c.deg=3, sp.nk=3, maxit=10000)
plot(fit$t, exp(fit$c), type="l", , xlab="t (day)", ylab="exp(c(t))")
title(main="Multiplicative trend")
filled.contour(fit$u1, fit$u2, exp(fit$mu[, , 1]))
title(main=expression(paste("Baseline intensity ", nu(u))), xlab="Longitude", ylab="Latitude")

```

trend_seas_s

*Trend and seasonality estimation for spatial Point Process Time Series***Description**

Fits seasonal additive model $\mu(u, t) = c(t) + \mu_{j(t)}(u)$ to log-intensity process $\log(\Lambda_t(u))$, where $c(t)$ is a polynomial and $\mu_1(u), \dots, \mu_d(u)$ are tensor-product splines.

Usage

```

trend_seas_s(x, rng, d = 1, r = length(x) - length(x)%d, c.deg = 1,
            sp.nk = 1, sp.deg = 3, maxit = 100, conf = 0.95)

```

Arguments

x	(n-list) Observations ($x[[i]]$ is a $m_i \times 2$ matrix, possibly $m_i=0$, first column is longitude, second column is latitude)
rng	(4-vector) Spatial range of the process (first two numbers are longitude range, the other two are latitude range)
d	(integer) Seasonal period (use default 1 for non-seasonal model)
r	(integer) Period of trend $c(t)$ (must be a multiple of d ; default is $n-n\%d$)
c.deg	(integer) Degree of polynomial $c(t)$
sp.nk	(integer) Number of spline knots per dimension for $\mu_j(u)$
sp.deg	(integer) Spline degree for $\mu_j(u)$
maxit	(integer) Maximum number of iterations
conf	(scalar) Confidence interval level (default is 0.95)

Value

u1	(ng-vector) Grid for evaluation of $\mu_j(u)$ (longitude)
u2	(ng-vector) Grid for evaluation of $\mu_j(u)$ (latitude)
mus	(ng x ng x d -array) Seasonal means $\mu_j(u)$ evaluated at $u1 \times u2$ ($mus[i,k,j] = \mu_j(u1[i], u2[k])$)
t	(vector) Grid for evaluation of $c(t)$ ($t = 1:n$)

c	(vector) Trend $c(t)$ evaluated at t
tt	(vector) Grid for evaluation of one cycle of $c(t)$ ($tt = 1:r$)
ct	(vector) One cycle of trend $c(t)$ evaluated at tt
eta	(vector) Basis coefficients for $c(t)$
thetas	(matrix) Basis coefficients for $\mu_j(u)$ (in rows)
ub_ct	(vector) Upper conf bound for $c(t)$
lb_ct	(vector) Lower conf bound for $c(t)$
ub_ect	(vector) Upper conf bound for $\exp(c(t))$
lb_ect	(vector) Lower conf bound for $\exp(c(t))$
ub_mus	(ng x ng x d -array) Upper conf bound for $\mu_j(u)$'s evaluated at $u1 \times u2$
lb_mus	(ng x ng x d -array) Lower conf bound for $\mu_j(u)$'s evaluated at $u1 \times u2$
ub_lmb	(ng x ng x d -array) Upper conf bound for $\exp(\mu_j(u))$'s evaluated at $u1 \times u2$
lb_lmb	(ng x ng x d -array) Lower conf bound for $\exp(\mu_j(u))$'s evaluated at $u1 \times u2$
Omega	(matrix) Covariance matrix of joint parameters

Author(s)

Daniel Gervini

References

Gervini, D., and Kopischke, S.A. (2006), "Trend and seasonality estimation for point-process time series." DOI: 10.48550/arXiv.2605.21884

Examples

```
data(crime)
fit <- trend_seas_s(x=crime$x, rng=crime$range, d=7, c.deg=3, sp.nk=3)
plot(fit$t, fit$c, type="l")
filled.contour(fit$u1, fit$u2, exp(fit$mus[, , 1]))
```

trend_seas_t

Trend and seasonality estimation for temporal Point Process Time Series

Description

Fits seasonal additive model $\mu(u, t) = c(t) + \mu_{j(t)}(u)$ to log-intensity process $\log(\Lambda_t(u))$, where $c(t)$ is a polynomial and $\mu_1(u), \dots, \mu_d(u)$ are splines.

Usage

```
trend_seas_t(x, rng, d = 1, r = length(x) - length(x)%d, c.deg = 1,
            sp.nk = 1, sp.deg = 3, maxit = 100, conf = 0.95)
```

Arguments

x	(n-list) Observations ($x[[i]]$ is a vector of length m_i , possibly $m_i=0$)
rng	(vector, length 2) Time range of the process
d	(integer) Seasonal period (use default 1 for non-seasonal model)
r	(integer) Period of trend $c(t)$ (must be a multiple of d ; default is $n-n\%d$)
c.deg	(integer) Degree of polynomial $c(t)$
sp.nk	(integer) Number of spline knots for $\mu_j(u)$
sp.deg	(integer) Spline degree for $\mu_j(u)$
maxit	(integer) Maximum number of iterations
conf	(scalar) Confidence interval level (default is 0.95)

Value

u	(vector) Grid for evaluation of $\mu_j(u)$
mus	(matrix) Seasonal means $\mu_j(u)$ (in columns) evaluated at u
t	(vector) Grid for evaluation of $c(t)$ ($t = 1:n$)
c	(vector) Trend $c(t)$ evaluated at t
tt	(vector) Grid for evaluation of one cycle of $c(t)$ ($tt = 1:r$)
ct	(vector) One cycle of trend $c(t)$ evaluated at tt
eta	(vector) Basis coefficients for $c(t)$
thetas	(matrix) Basis coefficients for $\mu_j(u)$ (in rows)
ub_ct	(vector) Upper conf bound for $c(t)$
lb_ct	(vector) Lower conf bound for $c(t)$
ub_ect	(vector) Upper conf bound for $\exp(c(t))$
lb_ect	(vector) Lower conf bound for $\exp(c(t))$
ub_mus	(matrix) Upper conf bound for $\mu_j(u)$ (in columns)
lb_mus	(matrix) Lower conf bound for $\mu_j(u)$ (in columns)
ub_lmb	(matrix) Upper conf bound for $\exp(\mu_j(u))$ (in columns)
lb_lmb	(matrix) Lower conf bound for $\exp(\mu_j(u))$ (in columns)
Omega	(matrix) Covariance matrix of joint parameters

Author(s)

Daniel Gervini

References

Gervini, D., and Kopischke, S.A. (2006), "Trend and seasonality estimation for point-process time series." DOI: 10.48550/arXiv.2605.21884

Examples

```
data(bikes)
fit <- trend_seas_t(x=bikes$x, rng=bikes$range, d=7, c.deg=3, sp.nk=5)
plot(fit$tt, fit$ct, type="l")
matplot(fit$u, exp(fit$mus), type="l", lty=1)
```

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